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MTH 236 - Assignment 8 key

$$1.) A = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\text{For any } \theta, \det(A) = \cos^2 \theta + \sin^2 \theta = 1 \neq 0.$$

$$A^{-1} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

$$2.) (A^k)(A^{-1})^k = \underbrace{AA \dots A}_{k \text{ TIMES}} \cdot \underbrace{A^{-1}A^{-1} \dots A^{-1}}_{k \text{ TIMES}}$$

$$= I \quad (\text{Simplifying from inside out})$$

$$\text{Also, } (A^{-1})^k (A^k) = \underbrace{A^{-1}A^{-1} \dots A^{-1}}_{k \text{ TIMES}} \cdot \underbrace{AA \dots A}_{k \text{ TIMES}}$$

$$= I$$

Therefore $(A^{-1})^k$ is both a left & right inverse of A^k . It follows that $(A^{-1})^k = (A^k)^{-1}$.

3.) Suppose P is a permutation matrix with rows $P_1, P_2, \dots, P_n$.

Then P^T is the matrix with columns $P_1^T, P_2^T, \dots, P_n^T$.

Each row P_k and column P_k^T has a single 1 in the same position and zeros elsewhere. No other row or column has a 1 in the same position. It follows that

$$P_i \cdot P_j^T = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

From which it follows that $PP^T = I$.

(Another approach is to recognize that P is an orthogonal matrix.)

- 4.) Suppose $AB = I$. Then, because $\text{rank}(AB) = n \leq \text{rank}(A)$
 AND $\text{rank}(AB) \leq \text{rank}(B)$,
 A AND B MUST BE INVERTIBLE.

Now,

$$AB = I \Leftrightarrow A^{-1}AB = A^{-1}I \Leftrightarrow B = A^{-1}$$

$$\Leftrightarrow BA = A^{-1}A = I$$

Therefore, we have $AB = I \Leftrightarrow BA = I$.

5.)

CHANGE-OF-BASIS MATRIX

$$= \left(\text{Rep}_D \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \text{Rep}_D \begin{pmatrix} 2 \\ 2 \end{pmatrix} \right)_{B,D}$$

$$0c_1 + 1c_2 = -1$$

$$4c_1 + 3c_2 = 1$$

$$c_2 = -1$$

$$c_1 = 1$$

$$0c_1 + 1c_2 = 2$$

$$4c_1 + 3c_2 = 2$$

$$c_2 = 2$$

$$c_1 = -1$$

$$\text{Rep}_D(\text{id}) = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}_{B,D}$$

6.) CHANGE-OF-BASIS MATRIX

$$= \left(\text{Rep}_D(1), \text{Rep}_D(X), \text{Rep}_D(X^2) \right)_{B,D}$$

$$c_1 X^2 + c_2 + c_3 X = 1 \Rightarrow c_1 = 0, c_2 = 1, c_3 = 0$$

$$c_1 X^2 + c_2 + c_3 X = X \Rightarrow c_1 = 0, c_2 = 0, c_3 = 1$$

$$c_1 X^2 + c_2 + c_3 X = X^2 \Rightarrow c_1 = 1, c_2 = 0, c_3 = 0$$

$$\text{Rep}_D(\text{id}) = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}_{B,D}$$

7.) Let $D = \text{BASIS FOR CODOMAIN} = \left\langle \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \right\rangle.$
 (I just made up a basis for $\mathbb{R}^3$.)

$$\begin{aligned} \text{Now } \text{Rep}_D(\text{id}) &= \left(\text{Rep}_D(\vec{\beta}_1), \text{Rep}_D(\vec{\beta}_2), \text{Rep}_D(\vec{\beta}_3) \right)_{B,D} \\ &= \begin{pmatrix} 3 & -1 & 4 \\ 2 & -1 & 1 \\ 0 & 1 & 4 \end{pmatrix}_{B,D} \end{aligned}$$

$$\text{Rep}_D(\vec{\beta}_1) = \begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix}_D \Rightarrow \vec{\beta}_1 = 3 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + 0 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 5 \end{pmatrix}$$

$$\text{Rep}_D(\vec{\beta}_2) = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}_D \Rightarrow \vec{\beta}_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{Rep}_D(\vec{\beta}_3) = \begin{pmatrix} 4 \\ 1 \\ 4 \end{pmatrix}_D \Rightarrow \vec{\beta}_3 = 4 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + 4 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 12 \\ 5 \\ 9 \end{pmatrix}$$

#7 CONTINUED ...

IT FOLLOWS THAT

$$B = \left\langle \begin{pmatrix} 3 \\ 2 \\ 5 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 12 \\ 5 \\ 9 \end{pmatrix} \right\rangle.$$

$$8.) \vec{p}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \vec{p}_2 = \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix}, \vec{p}_3 = \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix}$$

$$\vec{k}_1 = \vec{p}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

$$\vec{k}_2 = \vec{p}_2 - \text{proj}_{\vec{k}_1} \vec{p}_2 = \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix} + \frac{5}{14} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 33/14 \\ 24/14 \\ -27/14 \end{pmatrix}$$

$$\vec{k}_3 = \vec{p}_3 - \text{proj}_{\vec{k}_1} \vec{p}_3 - \text{proj}_{\vec{k}_2} \vec{p}_3 = \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix} - \frac{18}{14} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} - \frac{45/7}{171/14} \begin{pmatrix} 33/14 \\ 24/14 \\ -27/14 \end{pmatrix}$$

$\uparrow \frac{9}{7} \qquad \qquad \uparrow \frac{10}{19}$

$$= \begin{pmatrix} 9/19 \\ -9/19 \\ 3/19 \end{pmatrix}$$

$$\vec{k}_1 = (1 \ 2 \ 3)^T$$

$$\vec{k}_2 = \left(\frac{33}{14} \quad \frac{24}{14} \quad \frac{-27}{14} \right)^T$$

$$\vec{k}_3 = \left(\frac{9}{19} \quad \frac{-9}{19} \quad \frac{3}{19} \right)^T$$

OR

NORMALIZED

$$\vec{u}_1 = \left(\frac{\sqrt{14}}{14}, \frac{\sqrt{14}}{7}, \frac{3\sqrt{14}}{14} \right)^T$$

$$\vec{u}_2 = \left(\frac{11\alpha}{19}, \frac{8\alpha}{19}, \frac{-9\alpha}{19} \right)^T$$

$$\vec{u}_3 = \left(\frac{3\sqrt{19}}{19}, \frac{-3\sqrt{19}}{19}, \frac{\sqrt{19}}{19} \right)^T$$

$$\text{WHERE } \alpha = \sqrt{\frac{19}{14}}.$$

9.)

$$\begin{aligned} x - y - z + w &= 0 \\ x + z &= 0 \end{aligned} \Rightarrow \left(\begin{array}{cccc|c} 1 & -1 & -1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 \end{array} \right)$$

RREF

$$\downarrow \left(\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & -1 & 0 \end{array} \right)$$

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} -1 \\ -2 \\ 1 \\ 0 \end{pmatrix} z + \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} w$$

$$\text{Basis} = \left\langle \underbrace{\begin{pmatrix} -1 \\ -2 \\ 1 \\ 0 \end{pmatrix}}_{\vec{\beta}_1}, \underbrace{\begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}}_{\vec{\beta}_2} \right\rangle$$

$$\vec{k}_1 = \begin{pmatrix} -1 \\ -2 \\ 1 \\ 0 \end{pmatrix}$$

$$\vec{k}_2 = \vec{\beta}_2 - \text{proj}_{\vec{k}_1} \vec{\beta}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} - \frac{(-2)}{6} \begin{pmatrix} -1 \\ -2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1/3 \\ 1/3 \\ 1/3 \\ 1 \end{pmatrix}$$

NORMALIZE ...

$$\frac{\vec{k}_1}{\|\vec{k}_1\|} = \vec{u}_1 = \left(-\frac{\sqrt{6}}{6}, -\frac{\sqrt{6}}{3}, \frac{\sqrt{6}}{6}, 0 \right)^T$$

$$\frac{\vec{k}_2}{\|\vec{k}_2\|} = \frac{\vec{k}_2}{\frac{2\sqrt{3}}{3}} = \left(-\frac{\sqrt{3}}{6}, \frac{\sqrt{3}}{6}, \frac{\sqrt{3}}{6}, \frac{\sqrt{3}}{2} \right)^T$$

10.) IF THE ORIGINAL SET IS DEPENDENT,
THE GRAM-SCHMIDT PROCESS WILL
EVENTUALLY PRODUCE ZERO VECTORS.

IN FACT, IT WILL PRODUCE A ZERO VECTOR
WHenever you APPLY THE PROCESS TO A
VECTOR THAT IS A LINEAR COMBINATION OF
PRECEDING VECTORS.

11.) THE DOT PRODUCTS WILL BE ZERO, AND
THE PROCESS WILL GENERATE THE ORIGINAL
BASIS ITSELF.